

Preparation Guide

Synerduino STM

VERSIONS: F405, F411, H743

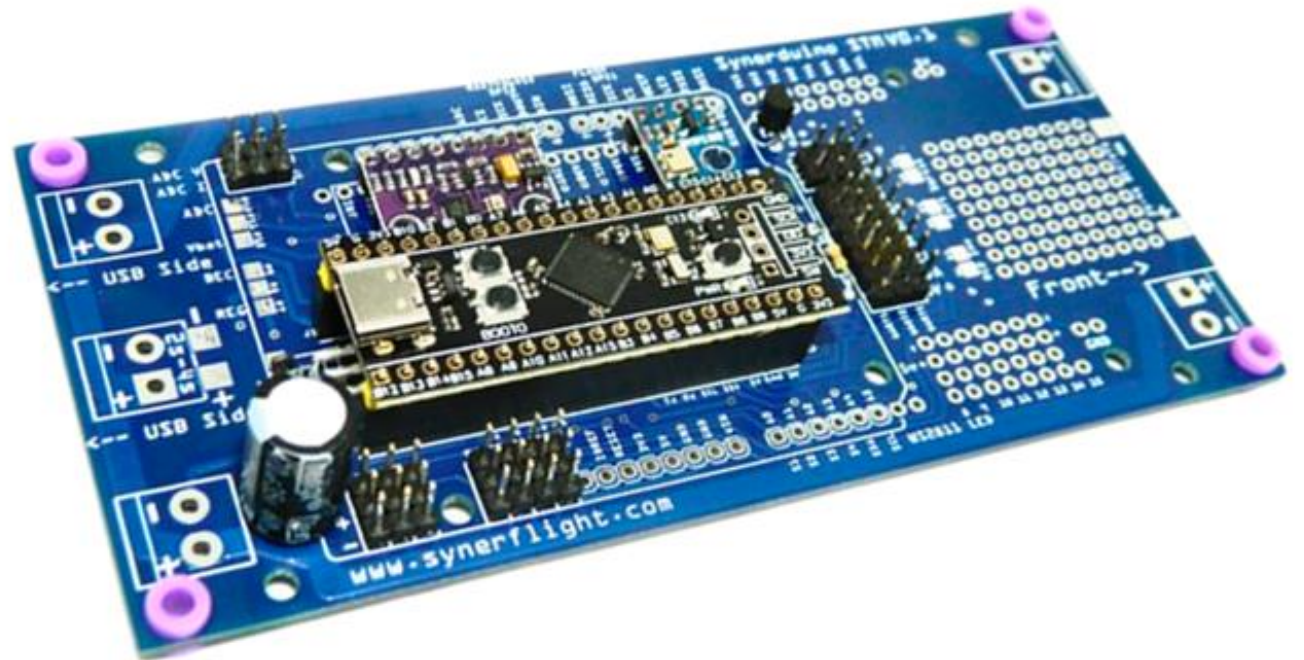
For more Information:
www.synerflight.com



INTRODUCTION

Preparing your Synerduino Board for Configuration and installation of Components

Soldering and Glue is require in this stage



F411 SELECTOR PADS

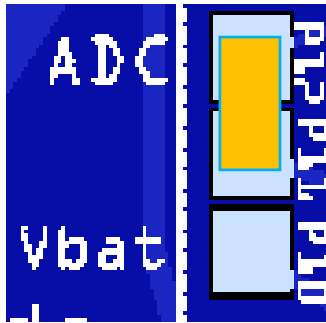
To Select two adjacent pads must be shorted with a solder jumper blob



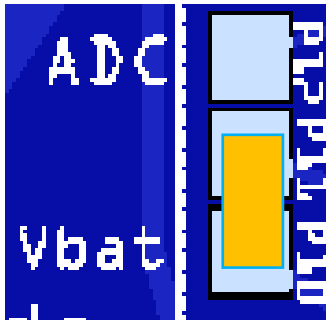
P9-P8 : BEC –this is use if you have a BEC powering through the ESC w/UBEC or an Standalone UBEC or Buck Converter Plug into S2 Pin **BEC input is 5V**



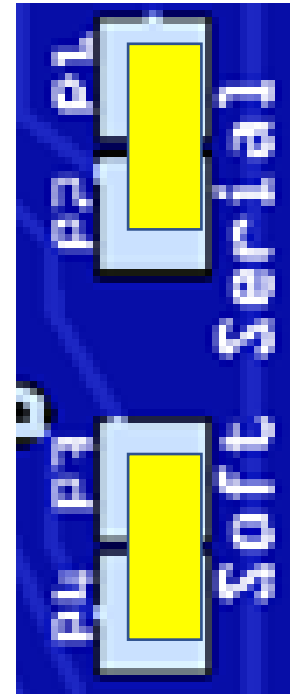
P8-P7 : REG –this is use if you just Run basics to power just the main drone board , GPS , Telemetry and Receiver



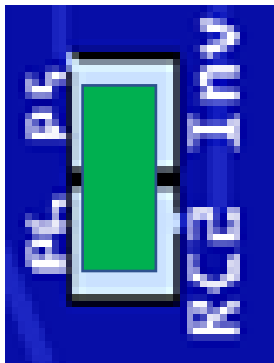
P12-P11 ADC Sensor Input



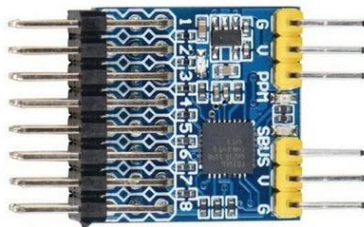
P11-P10 ADC Voltage Monitoring input



P1-P2 P3-P4 Softserial activates the TXSS and RXSS connection to the expansion pins for Prototyping board serial Connection



P5-P6 RC2 Inv : inverts the Sbus signals which activates the RC2 Sbus pin input to the UART2



SBUS Converters for Receivers that supports PPM and PWM only

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Note: the power rails would support upto 4s safely

For 6s setup this would require an external UBEC to supply 5V

F405 & H743 SELECTOR PADS



P16-P17 : BEC –this is use if you have a BEC powering through the ESC w/UBEC or an Standalone UBEC or Buck Converter Plug into S2 Pin **BEC input is 5V**

Default Onboard Regulator



Default ADC1 input

P18-P19 ADC activate Battery monitoring

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Note: the power rails would support only 2s 7.2V - 6s 24.8V safely

For 6s and Higher setup this would require an external UBEC to supply 5V

For ESCs with UBEC ensure it outputs 5V



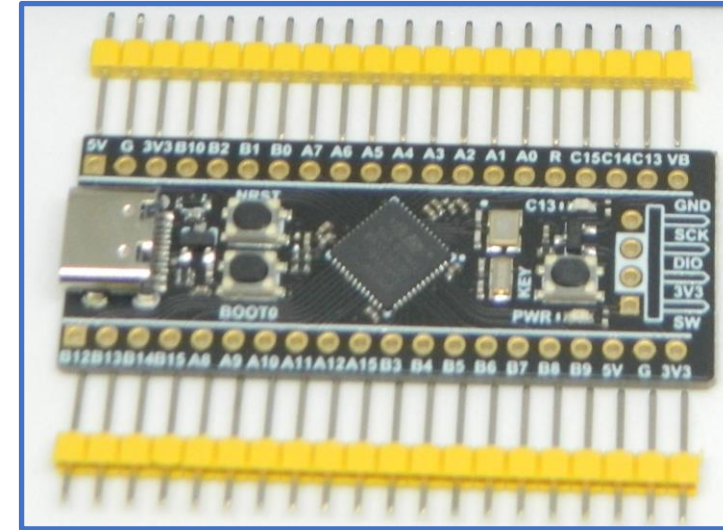
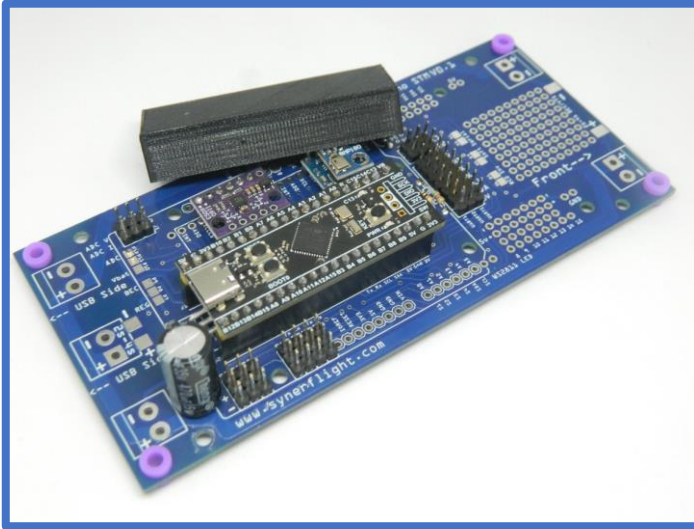
(H743 Boards) RC1 & RC2 PIN can be reassign to 3 different UARTs

UART2 for RC2-RX2

UART6 for RC6-RX6

To Select two adjacent pads must be shorted with a solder blob

BOARD PREPARATION



IMU Sensors must be covered with the provided housing glued into place using PVA white glue on the rim of the cover

Processor headers install on the underside and soldered in

